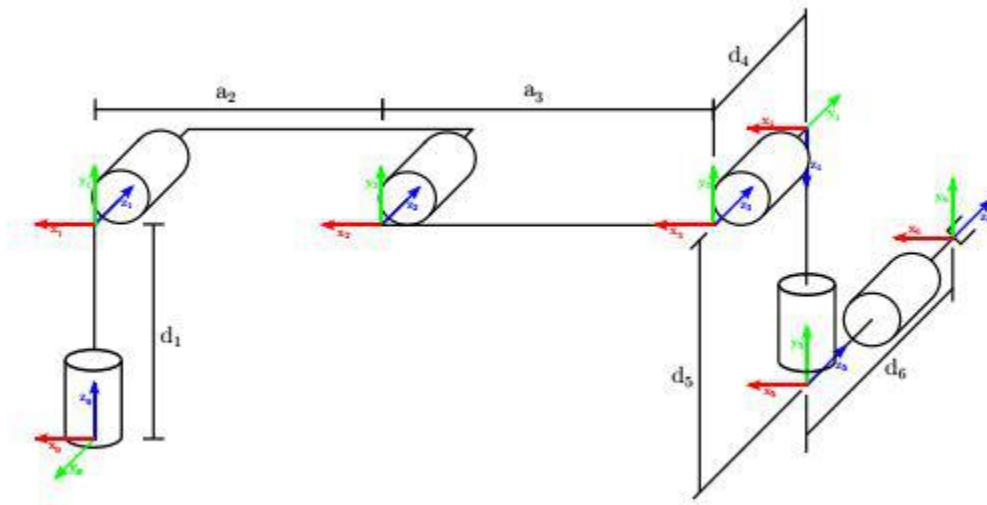


1、NC05 建模



2、NC05_Modified DH

	Theta[rad]	a[m]	d[m]	Alpha[rad]
Joint1	0	0	d1 = 0.240	0
Joint2	$-\pi/2$	0	0	$\pi/2$
Joint3	0	a2 = -0.400	0	0
Joint4	$-\pi/2$	a3 = -0.330	d4 = 0.135	0
Joint5	0	0	d5 = 0.120	$\pi/2$
Joint6	0	0	d6 = 0.088	$-\pi/2$

3、NC05_Standard DH

	Theta[rad]	a[m]	d[m]	Alpha[rad]
Joint1	0	0	d1 = 0.240	$\pi/2$
Joint2	$-\pi/2$	a2 = -0.400	0	0
Joint3	0	a3 = -0.330	0	0
Joint4	$-\pi/2$	0	d4 = 0.135	$\pi/2$
Joint5	0	0	d5 = 0.120	$-\pi/2$
Joint6	0	0	d6 = 0.088	0